



# Autonomous UV-C Robot Disinfection in Cleanrooms: Application & Qualification Case Study

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# Agenda

- The Challenge: Effective Contamination Control
- Robotics in Pharma
- Ultraviolet Germicidal Irradiation
- UV-C Autonomous Robot: Background, Benefits, Use-Cases
- Qualification Case Study
- Overall Qualification Process
- Take Aways



# The Challenge

# The Challenge: Effective Contamination Control

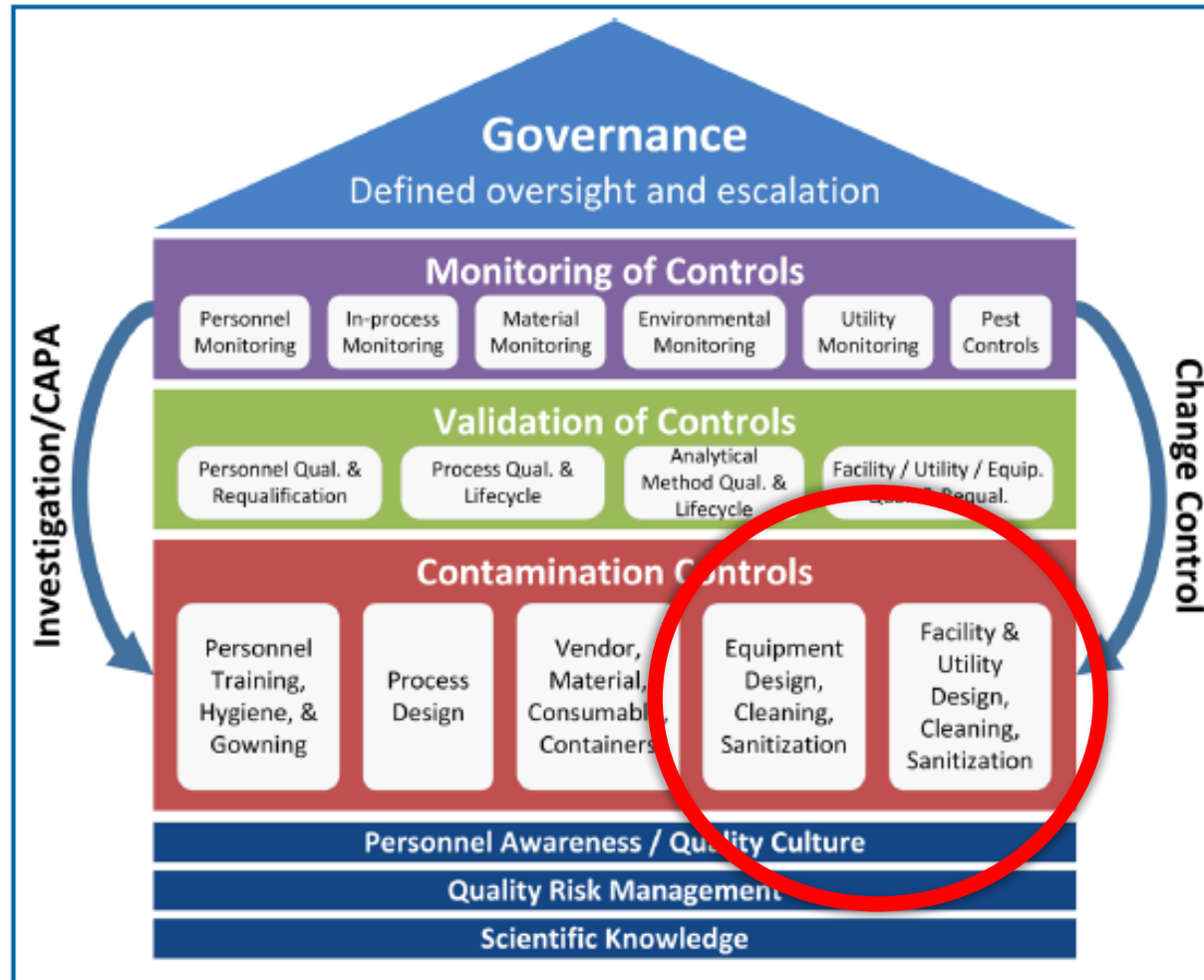
## Contamination Control Strategy (CCS):

A documented, risk-based strategy that defines the overall approach to identify, assess, control, and continuously review risks of microbial, endotoxin/pyrogen, and particulate contamination

“A CCS should be implemented across the facility in order to define all critical control points and assess the effectiveness of all the controls (design, procedural, technical and organisational) and monitoring measures employed to manage risks to medicinal product quality and safety. The combined strategy of the CCS should establish robust assurance of contamination prevention.”

– **Annex 1 Manufacture of Sterile Medicinal Products**

# The Challenge: Contamination Control



PDA Technical Report No. 90: Contamination Control Strategy Development in Pharmaceutical Manufacturing (2023)

# Personnel: Our Greatest Asset...and our Greatest Risk



- **Properly trained personnel are the foundation of pharmaceutical manufacturing quality & contamination control, however:**
  - Despite training, humans remain a primary source of contamination
  - Humans continuously shed microorganism (“mobile contamination sources”)
  - Human error: deviations from procedures, poor aseptic technique or behavior, etc
  - A robust CCS must therefore assume human fallibility and compensate through facility design, **automation (where feasible)**, procedural controls, and effective monitoring

# Robotics in Pharma

# Regulatory Position on Automation & Robotics

**FDA Guidance for Industry – cGMP (2014):** Automation of other process steps, **including the use of technologies such as robotics**, can further reduce risk to the product.



**EU GMP Annex 1:(2022):** The use of appropriate technologies (e.g. [...] **robotic systems**) should be considered to increase the protection of the product from potential extraneous sources of endotoxin/pyrogen, particulate and microbial contamination such as personnel...  
[...] **Robotics and automation of processes can also be considered to eliminate direct human critical interventions**

# Industry Position on Automation & Robotics

**ISPE GPG Pharma 4.0:**  
Robotics directly support  
Pharma 4.0's goal of  
**minimizing manual operations**  
where human presence a  
contamination risk.  
Robots natively generate digital  
records, supporting Pharma  
4.0's **data-centric** model.  
Automated execution reduces  
ALCOA+ risks associated with  
**manual documentation.**



**PDA Letter 2023<sup>1</sup>:** By having a robot  
performing a given operation,  
whether in an aseptic environment or  
not, one can assume that the robot is  
going to **repetitively execute the  
given instructions exactly in every  
cycle.** (...) we can say that the robot is  
the perfect solution for having the  
**certainty of having a selected  
standard operating procedure  
respected in every step,** with the  
possibility of **fully automatic tracking  
of operations performed directly  
stored in the batch record.**

<sup>1</sup>PDA Letter Robotics and Automation in  
Pharmaceutical Production: A paradigm shift led by EU  
GMP Annex 1, Andrea Tanzini (2023)

# The Pharmaceutical Manufacturing Robot Landscape

## Industrial Robotic Arms

*Aseptic Processing,  
Filling & Packaging*



## Collaborative Robots (Cobots)

*Flexible Small-Batch  
Operations*



## Autonomous Mobile Robots (AMRs & AGVs)

*Material Transport & Logistics*



## Cleanroom-Specific Robots

*Sterile & Isolator  
Environments*



## UV-C Disinfection Robots

*Automated Bioburden Reduction*



## Inspection & QC Robots

*High-Speed Visual Inspection*



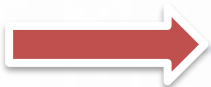
## Inspection & QC Robots

*High-Speed Visual Inspection*



## Laboratory & API Robots

*R&D & Analytical Automation*



Human Intervention



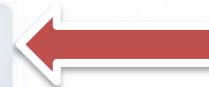
Sterility Assurance



Data Integrity



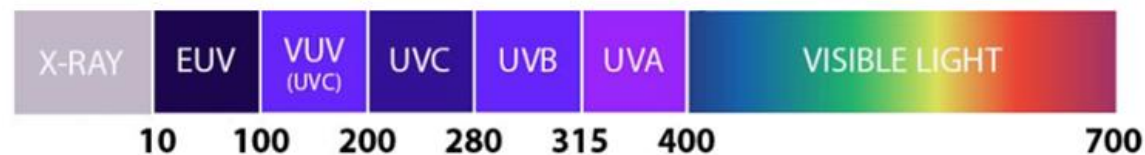
Contamination Control



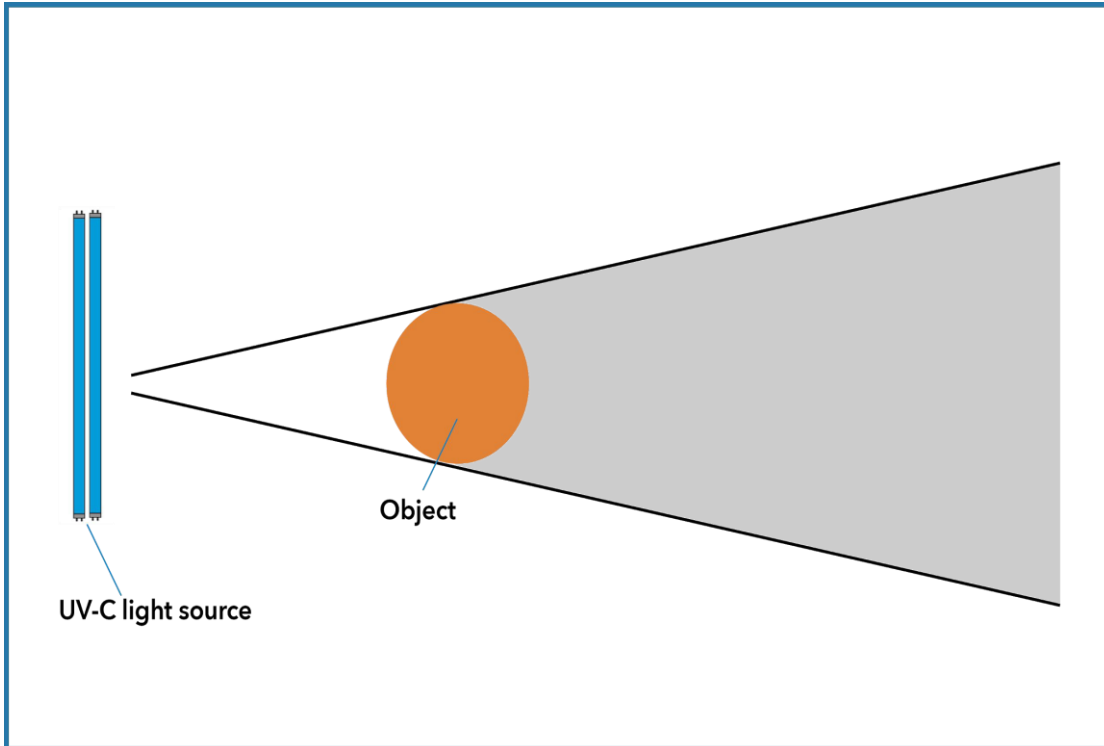
# Ultraviolet Germicidal Irradiation (UVGI)

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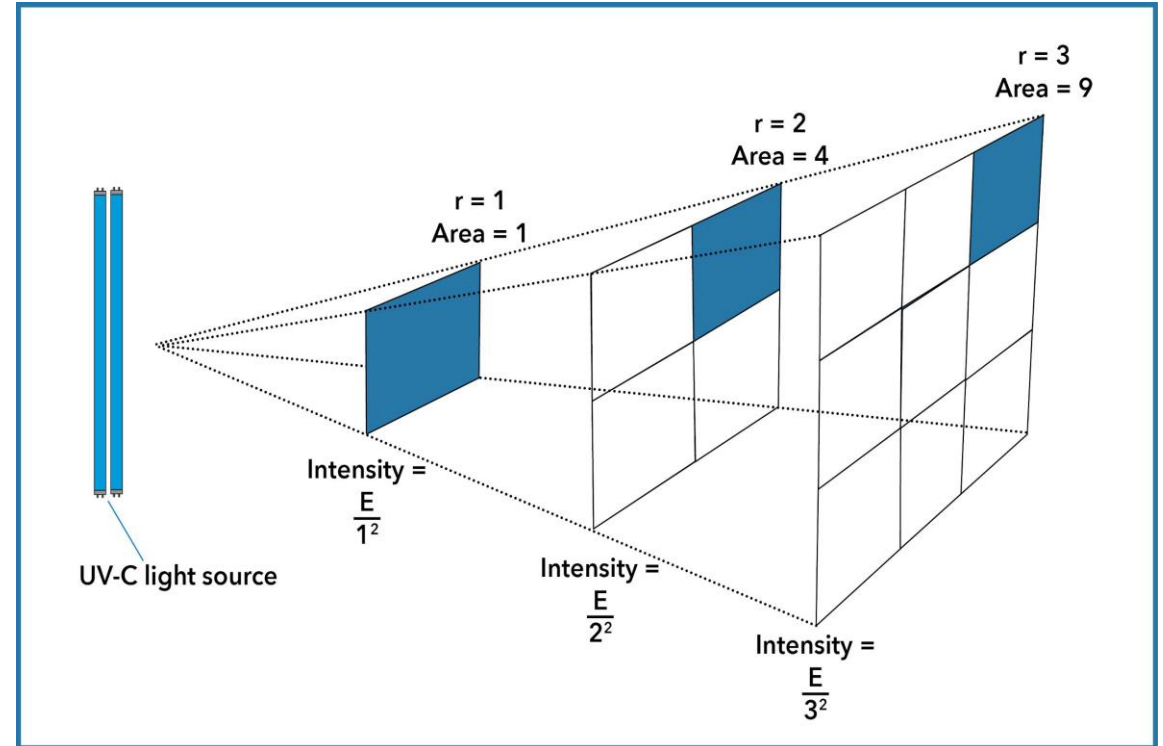
- UV-C light is a short-wavelength band of ultraviolet radiation, typically between 200 - 280 nm, with high photon energy
- UV kills cells because of the accumulation of DNA / RNA damage. If the damage is too extensive, a protein directs the **cell to apoptosis, or programmed cell death**
- Peak germicidal wavelength **~260 nm**. Mercury vapor lamps emit **~90-95% of energy at 253.7 nm**, optimizing germicidal effectiveness



# Ultraviolet Germicidal Irradiation (UVGI)



Light travels in a straight line - causing shadowing



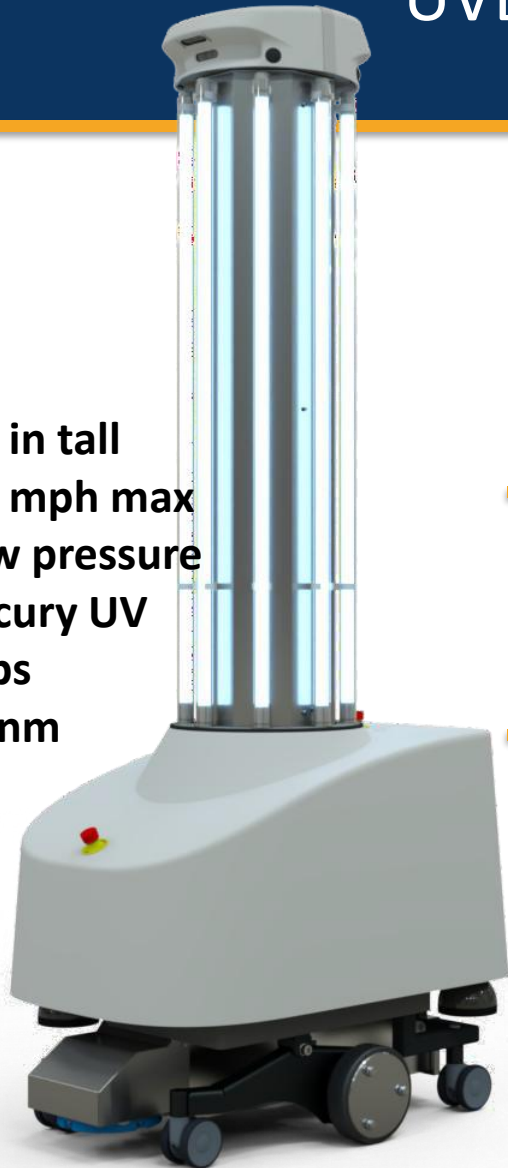
Inverse Square Law and distance from light source

UV-C autonomous robot motility overcomes shadowing and reduced intensity due to distance

# UVD Robot Pharma Background

# UVD Robot Pharma – Blue Ocean Robotics

- **70.3 in tall**
- **1.68 mph max**
- **8 low pressure mercury UV lamps**
- **254 nm**



Fully self-driving UV-C solution for whole room disinfection of cleanrooms – floor to ceiling

Designed to effectively and efficiently disinfect high-touch surfaces and high-traffic areas, reducing environmental bioburden

Robot mobility overcomes shadowing issues that are a major limitation of stationary UV-C systems

# UVD Robot Pharma – Safety



## 3 x3D Cameras

2 front and 1 rear-facing for detecting and avoiding objects in the vicinity

## 2 Emergency stop buttons

Stops disinfection immediately

## Audio warnings

Informs on safety information

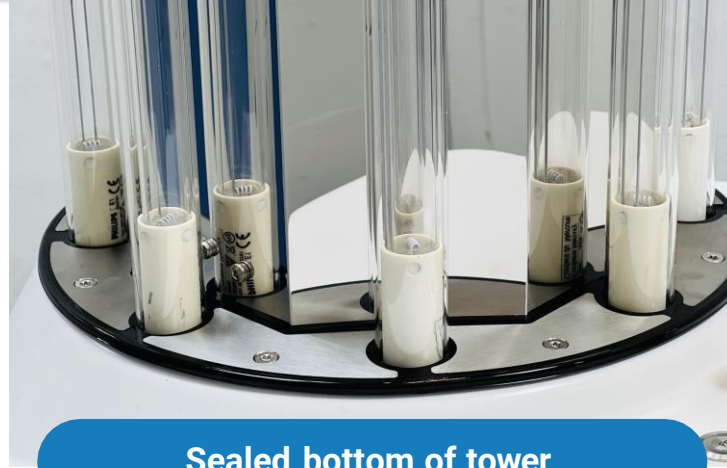
## 2 Lidar, safety laser scanners

1 front-facing and 1 rear-facing for walk and obstacle detection

# GMP Compliant Materials and Construction



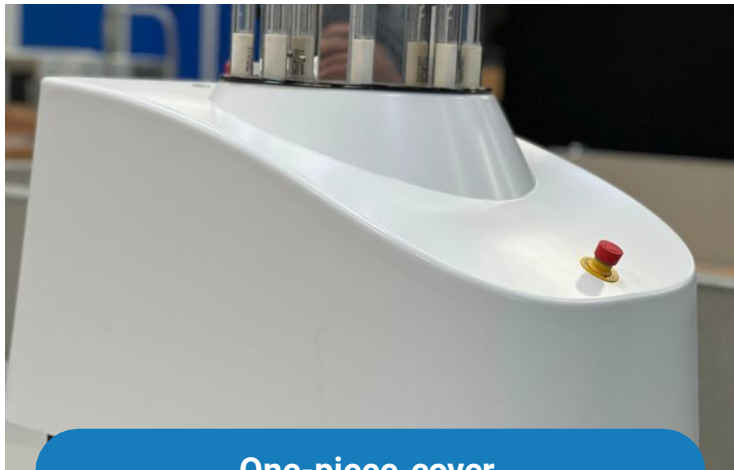
Cameras



Sealed bottom of tower



Sealed construction



One-piece cover



Stainless steel components



Contained/closed bottom of robot

# Benefits of Autonomous UV-C Robots for Cleanroom Disinfection

## Chemical-Free

- Dry process: reduce water & chemical disinfectant use
- No consumables
- Less residues
- Less material damage
- Helps meet sustainability goals

## Efficiency

- Quicker disinfection than manual (50-90% reduction in time)
- Automatic generation of documentation

## Quality

- Effective disinfection
- Repeatable & validated process
- Elimination of human error
- Frequent whole-room disinfection, reducing environmental bioburden
- Dosimeters verify target dose is achieved

## Compliance

- Traceability via 21 CFR Part 11 compliance (logs, audit trail, reports)

# Typical Pharma Use-Cases

## 1 Part chemical replacement

Objective: Faster C&D & higher production output

- High-speed disinfection for high-value manufacturing - boost efficiency with automation



## 2 Add-on large areas

Objective: Risk mitigation & business continuity

- Automated, repeatable disinfection - minimizing risk & ensuring compliance confidence



# Real-World Applications in Industry

- **European Fill-Finish Facility, Grade B Suite**
  - Using UV as primary daily disinfection
  - Risk Based supplemental disinfection is required, i.e. for shadowed areas
  - Target dose 100 mJ/cm<sup>2</sup> to focus on vegetative bacteria
  - Manual chemical disinfection reduced 60%-80% (~6 hrs to 1 hr)
  - Reduced sporicidal disinfection frequency from weekly to monthly
- **European Drug Substance Facility, Grade D Corridors**
  - Daily supplemental disinfection
  - Reduced EM excursions by 50%
- **US Fill-Finish CMO, Grades B – D (implementation in progress)**
  - Aim to use UV as primary mode of disinfection
  - Supplemented by manual disinfection as needed
  - Reduce the frequency of sporicidal disinfection based on daily whole-room daily disinfection



# Robot in Action

# UV Robot in Action - Video

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# Qualification Case Study

# Qualification Case Study

The screenshot shows the EJPPS website interface. At the top, there is a navigation bar with the EJPPS logo and links for Journals, Information & Instructions, Call for Papers & Advertising, EJPPS Board Members, and Contact. Below the navigation bar is a search bar and an ISSN 2633-6588 badge. The main content area features a user profile for lauraclark849, dated Oct 8, 2025, with a 17-minute read time. The article is identified as a Peer Review Article, Open Access, published on 8th October 2025. The title is 'Qualification of the Disinfection Efficacy of an Ultraviolet Autonomous Robot for Use in Pharmaceutical Clean Rooms.' The authors listed are S Capper<sup>2</sup>, C Cooke<sup>1</sup>, K Capper<sup>1\*</sup>, V Hamers<sup>3</sup>, A Gravett<sup>1</sup>, and J Bright<sup>1</sup>. The article is published in EJPPS | 303 (2025) and has a DOI link: <https://doi.org/10.37521/ejpps30307>. Navigation links include Back to Journals, Abstract, Conclusion, References, Appendixes, and Authors. The summary section begins with 'The aim of this study was to evaluate the efficacy of a UV-C disinfection robot intended for use on various cleanroom surfaces in the manufacturing facilities at AstraZeneca against a panel of different'.

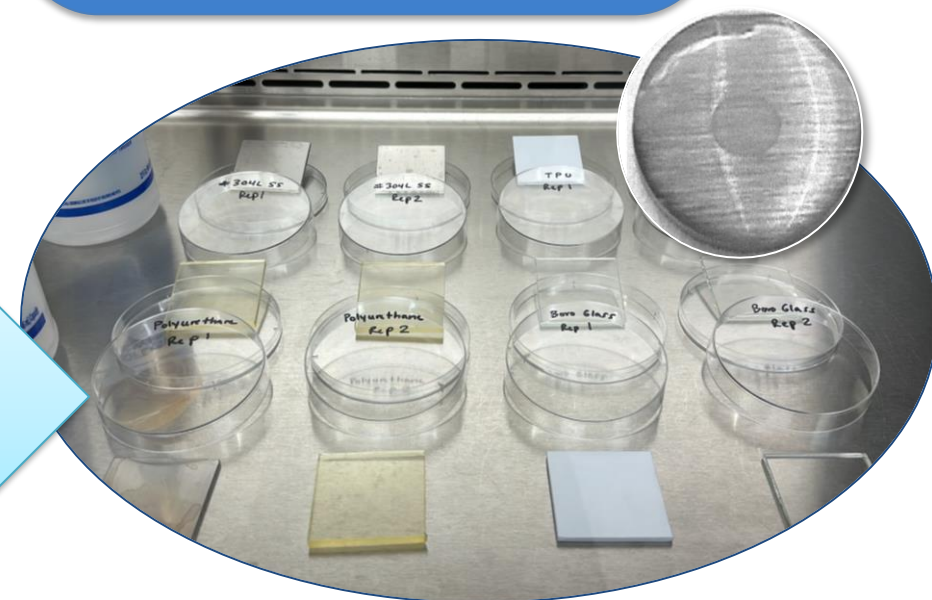
# Disinfectant Efficacy Testing Expectations

## ANNEX 1 – Section 4.34

*The disinfection process should be validated. Validation studies should demonstrate the suitability and effectiveness of disinfectants in the specific manner in which they are used and on the type of surface material, or representative material if justified, and should support the in-use expiry periods of prepared solutions*

**Standards:**  
USP <1072>  
ASTM E2197  
EN 1276, EN 1650, EN 13697,  
EN 13704, EN 16615

Efficacy testing is required for any modality of disinfection



# Qualification Case Study

- Evaluated the efficacy of a UV-C disinfection robot intended for use on various cleanroom surfaces in the company's manufacturing facilities against a panel of compendial and environmental microorganisms
- Based on USP <1072> and Surface Challenge Test Method (EN 13697)
- Microorganisms were inoculated onto coupons made of glass, stainless steel, and vinyl
- Coupons were exposed to UV at multiple dose-levels (mJ/cm<sup>2</sup>) and LRV was calculated



# Test Set-Up



Figure 1a. UVC Tower set up in the laboratory. The boards in the room were to attach the coupons two metres distance from the light Figure 1b. The black cloth was used to protect the control coupons from the light.



Figure 4. Coupons of vinyl, glass and steel with *Aspergillus brasiliensis* spores inoculated. The UVKEY and ILT2400 dose meter are in place and set to zero prior to start.

# UV Doses Tested (mJ/cm<sup>2</sup>)

Vegetative Organisms	Bacterial Spores	Mold Spores
0	0	0
5	20	20
10	40	40
15	60	80
20	80	100
25	100	200
50	200	500
100		700

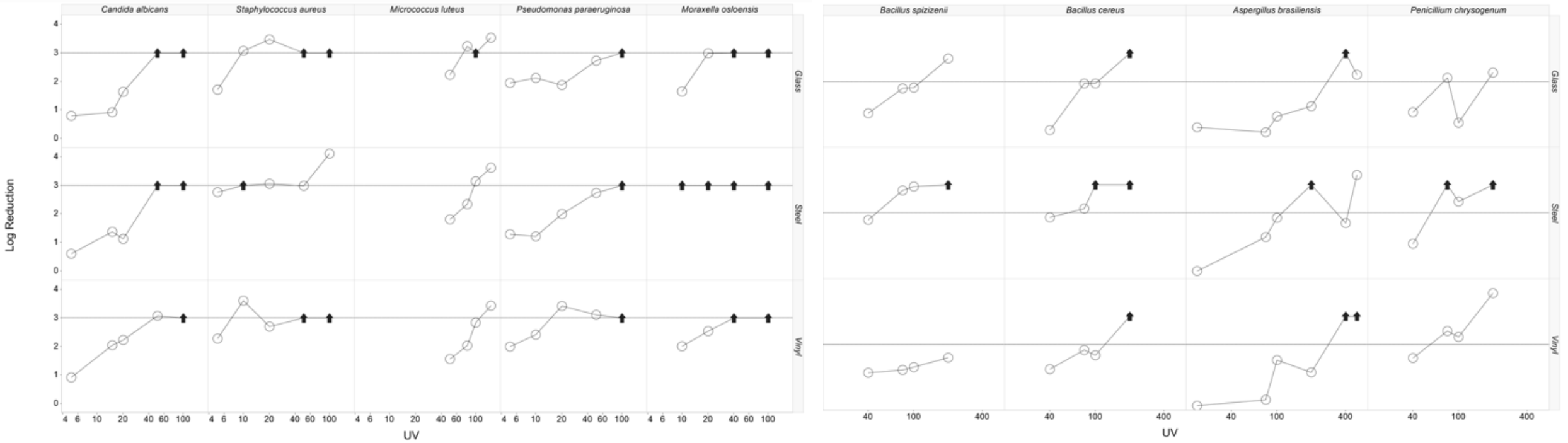
# Dose Needed for Required LRV Across All Surfaces

Organism	Type	Target Log Reduction	Dose mJ/cm <sup>2</sup>
<i>Aspergillus brasiliensis</i>	Fungal spores	2-log	500
<i>Bacillus subtilis (spizizenii)</i>	Bacterial spores	2-log	>200
<i>Penicillium chrysogenum (En.I.)</i>	Fungal spores	2-log	200
<i>Bacillus cereus (En.I.)</i>	Bacterial spores	2-log	200
<i>Micrococcus luteus (En.I.)</i>	Gram + cocci	3-log	150
<i>Staphylococcus aureus</i>	Gram + cocci	3-log	100
<i>Pseudomonas aeruginosa</i>	Gram - rods	3-log	100
<i>Candida albicans</i>	Yeast	3-log	50
<i>Moraxella osloensis (En.I.)</i>	Gram - cocci	3-log	40

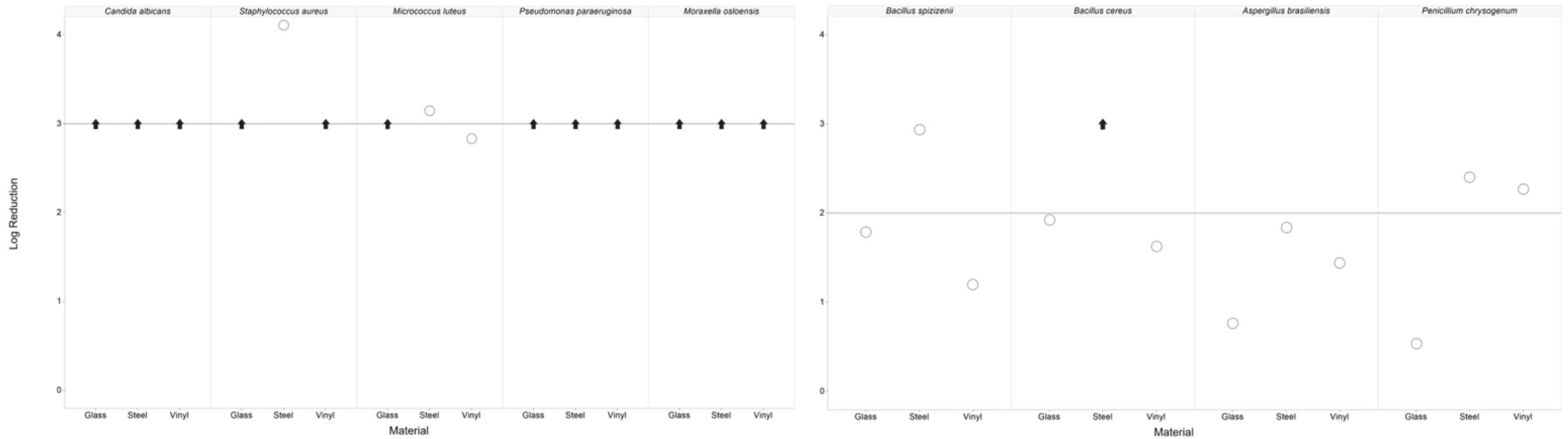
# LRV Achieved at 100 mJ/cm<sup>2</sup>

Organism	Type	Surface type (worst case)	Target Log Reduction	Log Reduction Achieved
<i>Penicillium chrysogenum (En.I.)</i>	Fungal spores	Glass	2-log	0.3 - 0.9
<i>Aspergillus brasiliensis</i>	Fungal spores	Glass	2-log	0.5 - >2.0
<i>Bacillus subtilis (spizizenii)</i>	Bacterial spores	Vinyl	2-log	1.1 - 1.3
<i>Bacillus cereus (En.I.)</i>	Bacterial spores	Vinyl	2-log	1.4 - >2.0
<i>Micrococcus luteus (En.I.)</i>	Gram + cocci	Vinyl	3-log	2.6 - >3.0
<i>Candida albicans</i>	Yeast	All	3-log	>3.0
<i>Staphylococcus aureus</i>	Gram + cocci	All	3-log	>3.0
<i>Pseudomonas aeruginosa</i>	Gram - rods	All	3-log	>3.0
<i>Moraxella osloensis (En.I.)</i>	Gram - cocci	All	3-log	>3.0

# Death Curves



# Surface Material Comparison



# Exposure Times

Organisms	Dose for 2 or 3 LRV	UV-C Exposure Time (sec) at 1 m distance
<b>Fungal Spores:</b> <ul style="list-style-type: none"> <li><i>Aspergillus brasiliensis</i></li> <li><i>Penicillium chrysogenum (En.I.)</i></li> </ul>	500 mJ/cm <sup>2</sup> 200 mJ/cm <sup>2</sup>	74 sec 185 sec
<b>Bacterial Spores:</b> <ul style="list-style-type: none"> <li><i>Bacillus subtilis (spizizenii)</i></li> <li><i>Bacillus cereus (En.I.)</i></li> </ul>	200 mJ/cm <sup>2</sup> 200 mJ/cm <sup>2</sup>	74 sec
<b>Gram-Positive Bacteria:</b> <ul style="list-style-type: none"> <li><i>Micrococcus luteus (En.I.)</i></li> <li><i>Staphylococcus aureus</i></li> </ul>	150 mJ/cm <sup>2</sup> 100 mJ/cm <sup>2</sup>	56 sec 37 sec
<b>Yeast</b> <ul style="list-style-type: none"> <li><i>Candida albicans</i></li> </ul>	50 mJ/cm <sup>2</sup>	18 sec
<b>Gram-Negative Bacteria:</b> <ul style="list-style-type: none"> <li><i>Pseudomonas aeruginosa</i></li> <li><i>Moraxella osloensis (En.I.)</i></li> </ul>	100 mJ/cm <sup>2</sup> 40 mJ/cm <sup>2</sup>	37 sec 15 sec

# Qualification Case Study Conclusions

- ▶ **100 mJ/cm<sup>2</sup>** was chosen for normal operation based on effective inactivation of vegetative bacteria and yeast
- ▶ **Higher doses (>200 mJ/cm<sup>2</sup>)** are required for remediation of spore-forming organisms and a sporicidal cycle can be implemented in reaction environmental monitoring results
- ▶ **Material degradation determined to be minimal** (data not shown) and identified UV-sensitive materials will be replaced at defined frequencies
- ▶ **UV will be part of an overall cleaning and disinfection program, with periodic manual disinfection**

# Overall Qualification Process

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## Equipment and Software Qualification

- C&Q Plan
- URS
- Quality Risk Assessment
- Design Qualification
- Factory Acceptance Testing
  - UV light intensity
- Installation and Operating Qualification
  - Cleanroom mapping
  - Configuration verification
  - Dosimeter (UV dose verification) test
- Disinfection cycle development per cleanroom
- Requalification
  - UV light intensity
  - Verification of room layouts

## Disinfection Efficacy Testing

- Compendial organisms
- Site specific organisms
- Cleanroom materials
- Log reduction - USP <1072>

## Site Implementation

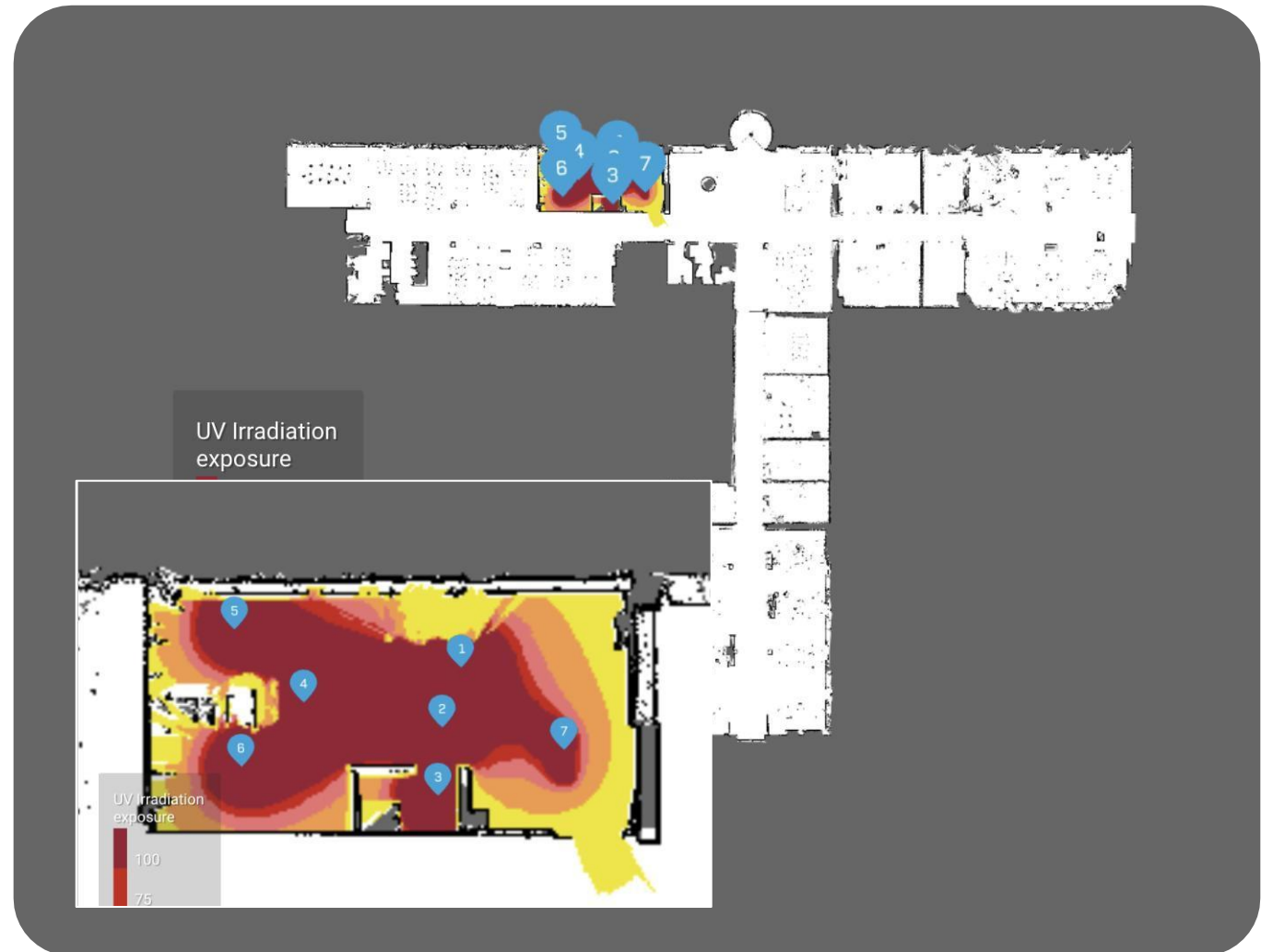
- SOP development / updates to include UV disinfection into disinfection program
  - Cleanrooms / zones
  - Frequency
  - Integration with chemical disinfection

## Performance Qualification

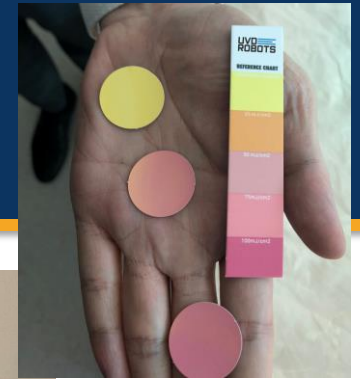
- Verify efficacy of cleaning & disinfection program in operation with implementation of UVD Robot
- Daily environmental monitoring sampling over a time frame
- Dependent on application of the UVD Robot / site specific

# Installation & Cycle Development

- 1 Scanning (mapping) of the entire area
- 2 Input for “master setup” of area(s)
- 3 Create disinfection run(s) / room(s)
- 4 Test and validation with dosimeter stickers



# Dosimeter Test



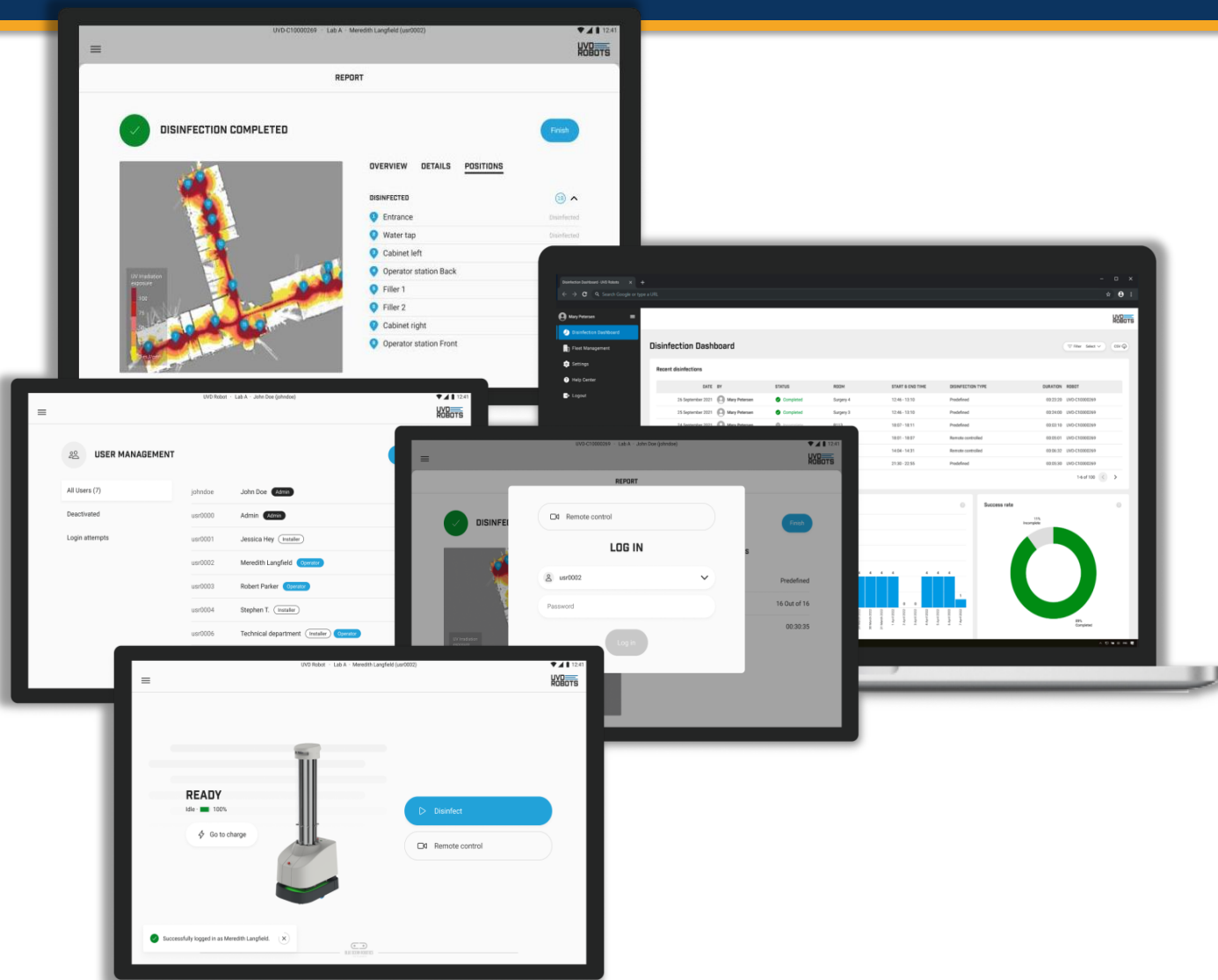
No UV	25 mJ/cm <sup>2</sup>	50 mJ/cm <sup>2</sup>	75 mJ/cm <sup>2</sup>	100 mJ/cm <sup>2</sup>
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Dosimeter sticker - Before

Dosimeter sticker - After



# Electronic Report




# Electronic Report

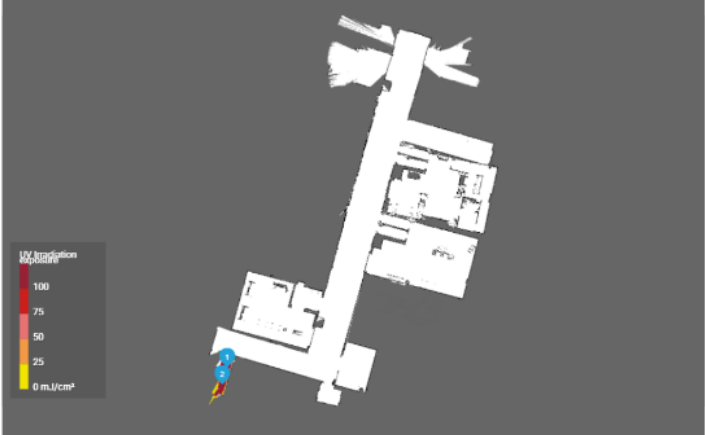
## Disinfection Report

**DISINFECTATION COMPLETE**

Room: RM A-1500B Jan.  
 Department: -  
 Robot name: 10000606



Date: 09 Apr 2026  
 Report exported from timezone: UTC-04:00  
 Disinfection ID: 69d7e5b4f4c368cc1d3250d0



### DETAILS

Disinfection mode	Predefined
Start time	09 Apr 2026 - 13:45
Started by	NathanB
Disinfection finished	09 Apr 2026 - 13:56
Finished by	NathanB
UV-C light duration	00:03:18
Total duration	00:10:45
Positions disinfected	2
Positions remaining	0
Positions failed driving to	


### INTERRUPTIONS

Walk detected	2
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## Disinfection Report

**DISINFECTATION COMPLETE**

Room: RM A-1500B Jan.  
 Department: -  
 Robot name: 10000606



Date: 09 Apr 2026  
 Report exported from timezone: UTC-04:00  
 Disinfection ID: 69d7e5b4f4c368cc1d3250d0

### DISINFECTATION LOG

13:45	Disinfection preparation started	NathanB
13:46	Disinfection started	NathanB
13:49	Warmup complete	
13:50	Disinfection interrupted: Walk detected.	
13:50	Safe conditions restored.	
13:51	Disinfection interrupted: Walk detected.	
13:51	Safe conditions restored.	
13:53	Disinfection resumed.	
13:53	Warmup complete	
13:55	Disinfection completed	
13:56	Disinfection report submitted	NathanB

# Take Aways

# Take Aways

- ▶ **Regulatory Alignment:** EU GMP Annex 1 and FDA guidance actively encourage automation and robotics to reduce human-derived contamination risk as part of a comprehensive CCS
- ▶ **Proven UV-C Efficacy:** UV-C germicidal irradiation at ~254 nm delivers effective microbial inactivation; robot mobility overcomes shadowing and distance limitations of stationary UV-C systems
- ▶ **Chemical-Free:** Dry process, consumable and residue free, supporting sustainability goals and reducing personnel exposure to chemicals
- ▶ **Operational Impact:** Real-world implementations demonstrate 60–80% reduction in manual disinfection time, 50% fewer EM excursions, and reduced sporicidal disinfection frequency

# Take Aways

- ▶ **Efficacy Qualification Results:** A standard dose of 100 mJ/cm<sup>2</sup> achieves ≥3-log reduction for vegetative organisms on common cleanroom surface materials and higher doses can be applied for sporicidal cycles targeting bacterial and fungal spores
- ▶ **Best Practice – Integrated Disinfection Program:** Daily autonomous UV-C disinfection as the primary mode, supplemented by manual chemical disinfection, delivers frequent, comprehensive whole-room coverage of floors, walls, ceilings, and touchpoints
- ▶ **Defined Qualification Pathway:** Equipment qualification, disinfection efficacy testing (per USP <1072>/EN 13697), and dosimeter-verified cycle development provide a robust, risk-based framework adaptable to any cleanroom environment

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# Thank You!

Questions?